

1 **Movement trajectories as a window into the dynamics of emerging neural representations**

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8 **Abstract**

9 Transforming sensory inputs into meaningful neural representations is critical to adaptive behaviour
10 in everyday environments. While non-invasive neuroimaging methods are the de-facto method for
11 investigating neural representations, they remain expensive, not widely available, time-consuming,
12 and restrictive in terms of the experimental conditions and participant populations they can be used
13 with. Here we show that movement trajectories collected in online behavioural experiments can be
14 used to measure the emergence and dynamics of neural representations with fine temporal
15 resolution. By combining online computer mouse-tracking and publicly available neuroimaging (MEG
16 and fMRI) data via Representational Similarity Analysis (RSA), we show that movement trajectories
17 track the evolution of visual representations over time. We used a time constrained face/object
18 categorization task on a previously published set of images containing human faces, illusory faces and
19 objects to demonstrate that time-resolved representational structures derived from movement
20 trajectories correlate with those derived from MEG, revealing the unfolding of category
21 representations in comparable temporal detail (albeit delayed) to MEG. Furthermore, we show that
22 movement-derived representational structures correlate with those derived from fMRI in most task-
23 relevant brain areas, faces and objects selective areas in this proof of concept. Our results highlight
24 the richness of movement trajectories and the power of the RSA framework to reveal and compare
25 their information content, opening new avenues to better understand human perception.

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28 **Introduction**

29 The human brain's astounding capacity for transforming sensory input into meaningful mental
30 representations enables our adaptive behaviour in complex and continuously changing environments.
31 While this capacity is now being increasingly investigated using neuroimaging, we show in this study
32 that low-cost and widely available behavioural measures, human movement trajectories in particular,
33 remain incredibly valuable to gain insight into the dynamics of emerging neural representations.
34 Indeed, behavioural measures, such as reaction time and eye-tracking, have been for decades our
35 main window into mental representations enabling gaining critical understanding of human cognition
36 ¹⁻⁵. The use of computer mouse-tracking movement trajectories is a more recent development in the
37 behavioural toolbox ⁶⁻⁹. Mouse-tracking involves the continuous tracking of cursor trajectories
38 towards one out of two or multiple choices, which has been found to be especially useful for
39 measuring non-explicit processes such as self-control, emotion, ambivalence, moral and subliminal
40 cognition¹⁰⁻¹⁴. Most importantly, movement trajectories have been proposed to inform not only about
41 the end point of decisional processes, but also the temporal dynamics of decisions, revealing the
42 emergence and duration of underlying neural representations ^{6,9,15-17}.

43 However, the extent to which movement trajectories can index the continuous unfolding of
44 cognitive processes, and more specifically, the transformation of visual inputs into meaningful neural
45 representations, remains controversial ¹⁸. It is still highly debated whether movements, especially
46 when performed under time constraints, can be modified by cognition once their execution has
47 started. There are indeed studies suggesting that certain changes in trajectory might not be visually
48 informed ¹⁹, that early visual perception might not be accessible by cognition ²⁰, that the variability of
49 movement outcomes might be mainly related to preparatory (pre-movement) neural activity ^{21,22}, and
50 that only single motor plans (i.e., a single choice, instead of competition among choices) would be
51 represented in the motor cortex ²³, thus challenging the hypothesis that the time-course of emerging
52 neural representations can be captured via movement trajectories.

53 By combining movement trajectories and neuroimaging data, we show in this study that
54 movement trajectories can provide a sensitive index of dynamic of neural representations. We show
55 that observers' mouse trajectories reveal the time course of decisional processes, capturing
56 information about early visual representations and following their evolution (albeit delayed) towards
57 their final stable state, instead of only reflecting the end product of decisional processes (i.e., a button
58 press). We used publicly deposited neuroimaging data from Wardle et al. (2020) ²⁴ which explored the
59 time-course and brain areas supporting illusory face representations (face pareidolia). This
60 phenomenon occurs when non-face stimuli elicit face perception due to their face-like visual features
61 ^{25,26}. Using images of human faces, pareidolic objects and non-pareidolic objects in combination with
62 Magnetoencephalography (MEG) and functional Magnetic Resonance Imaging (fMRI), the
63 aforementioned study revealed that illusory face representations emerge in earlier stages of visual
64 processing, being resolved as objects later on. Using Representational Similarity Analysis (RSA), we
65 compared these previously published neuroimaging data with mouse-tracking data we collected in an
66 online face vs. object categorization task. We show that representational structures derived from
67 movement trajectories matched those derived from MEG, following their temporal dynamics, albeit
68 delayed. Furthermore, movement trajectories representational structures were found to be especially
69 concordant with those derived from face and object selective brain areas as revealed by fMRI. Our
70 results show that movement trajectories capture representational dynamics by reflecting individual
71 stimuli differences, including their earlier visual processing stages, demonstrating decisive advantages
72 over other behavioural measures focused on the end point of decisional processes only.

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74 **Results**

75 We recorded mouse trajectory data from a group of 77 online observers as they performed a
76 face vs. object categorization task on the stimuli from Wardle et al. (2020)²⁴ (Figure 1A). To encourage
77 participants to begin their classification movement early, each trial automatically terminated 800ms
78 after stimulus presentation, or else when the participant clicked on a response box. Despite this time
79 constraint, analysis of mouse trajectory endpoints showed that participants were highly accurate in
80 categorising all three image categories (85.3, 80.68 and 82.36% for faces, pareidolic objects, and
81 objects, respectively). Category information contained in trial-by-trial trajectories (see single trial
82 examples in Figure 1B) was also reflected in conditional mean horizontal cursor position (Figure 1C):
83 Trajectories corresponding to face and object images diverged from each other soonest (from 325ms),
84 followed by those for faces and pareidolic objects (from 330ms). Trajectories corresponding to
85 pareidolic objects and normal objects separated comparatively later (from 375ms) (p
86 $<.05$; paired t -tests, FDR-corrected, $q=0.05$), with pareidolic object trajectories showing more
87 attraction towards the face response box between 300-800ms (Figure 1C, inset). Note participants
88 showed a slight initial bias towards responding 'face' (see Figure 1C&E), which could be caused by
89 several factors (e.g., specialised face processing or treating it like a face vs not-face task), but this bias
90 does not influence our analyses as we only examined relative position differences across exemplars.

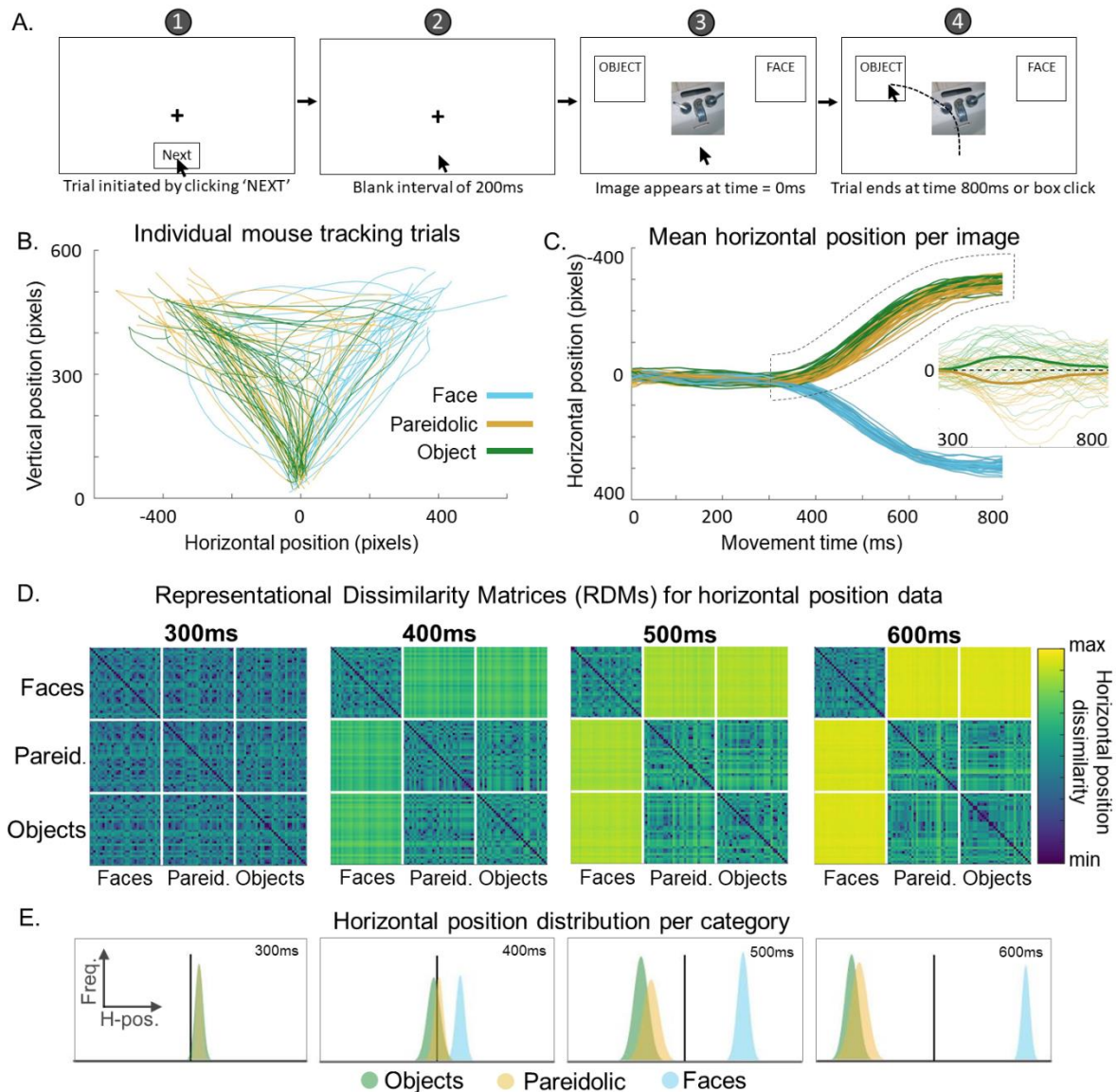
91 Our primary goal was to examine the degree of representational overlap between our
92 movement trajectory data and existing neuroimaging data for the same stimuli. We used
93 Representational Similarity Analysis (RSA)²⁷ to abstract away from the native measurement units for
94 these different datasets, projecting category distinctions reflected in MEG signals and horizontal
95 position mouse trajectory data into the information domain via representational dissimilarity matrices
96 (RDMs). Since the horizontal x-axis is the relevant dimension of categorization in our paradigm (i.e. go
97 left for faces, go right for objects), the RDM series derived from time-resolved x-position data enables
98 us to evaluate the emergence of category representations reflected in the unfolding movement
99 trajectory (Figure 1D). We constructed these by calculating the pairwise trajectory distance along the
100 x-axis (in pixels) between images for every time point (See Methods for details).

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106 **Figure 1.** Mouse-tracking movement trajectory data. **A. Paradigm schematic.** We recorded online
 107 observers' mouse trajectories in a face vs. object categorization task across 96 individual images (32
 108 faces, 32 pareidolic objects and 32 matched objects) as used by Wardle et al. (2020)²⁴. We added a
 109 further 32 face images to equalise the probability of faces/objects, but did not include these additional
 110 face images for analysis. We instructed participants to only categorize human faces as faces, such that
 111 both pareidolic objects and normal objects had to be categorized as objects. **(1)** Each trial sequence
 112 began with a central fixation cross and a "Next" button that participants clicked on to initiate the trial.
 113 **(2)** When the trial commenced, participants first saw a 200ms blank interval to promote readiness for
 114 movement. **(3)** At time=0, either a face, pareidolic object or matched object appeared at fixation,
 115 along with two response boxes in the upper left and right corners of the screen. All images were
 116 presented once per block, and there were four blocks in total. The positions of the 'OBJECT' and 'FACE'
 117 response boxes swapped halfway through the experiment (i.e., after two blocks), with their initial
 118 positions counterbalanced across participants to guard against any right/left response biases. **(4)**
 119 Participants were instructed to move the cursor and click the appropriate response box as fast as
 120 possible, with each trial terminating 800ms after stimulus onset (or on box click). Both cursor landings
 121 and clicks on the correct box were considered as correct trials. Both correct and incorrect trials were

122 included in subsequent analyses. **B. Individual mouse trajectories.** Individual mouse trajectory data
123 for one block from a representative participant (96 trials). **C. Mean horizontal position over time for**
124 **each exemplar in each category.** We took the horizontal component of the cursor movement (i.e., x-
125 coordinate) as a time-resolved measure of the unfolding categorization response. For each image, we
126 averaged x-position at each timepoint first within and then across participants (N=77), using these
127 summary scores for further analyses. **Inset:** Image-wise deviation from the mean trajectory for objects
128 and pareidolic objects. To visualise the distinction between object and pareidolic objects more clearly,
129 we subtracted the grand mean from each image's mean trajectory between 300 and 800ms (indicated
130 by the dashed window in the main plot). Trajectories for objects and pareidolic objects separate in
131 opposite directions, with pareidolic trajectories showing greater attraction towards the 'FACE'
132 response box. Thick lines are the averaged mean-subtracted trajectories for each category. **D.**
133 **Representational dissimilarity matrices (RDMs) for horizontal position data.** RDM for movement
134 data illustrate the representational structure across tested images based on the categorization
135 movement data. We constructed the RDM at each timepoint by taking the pairwise difference in pixels
136 along the horizontal axis between the mean trajectory for each image. This resulted in a 96x96 matrix
137 with 4186 unique pairwise combinations at each time point from 5-800ms after stimulus onset (step
138 size = 5ms). RDMs at 300, 400, 500 and 600ms are shown for reference. Dissimilarities are shown as
139 $\log_2(\text{distance})$ for display purposes. **E. Category distributions of horizontal position.** The distributions
140 of horizontal positions for each object grouped by category are shown as histograms at 300, 400, 500
141 and 600ms. Faces started to separate from objects and pareidolic objects around 400ms, and remain
142 separate over time. While the difference between pareidolic objects and objects was smaller than
143 their difference to faces (given that both pareidolic objects and objects were categorized as objects),
144 the distributions for pareidolic objects and objects remained offset, with the pareidolic object
145 distribution indicating differences in their movement trajectory profiles and an attraction effect of
146 faces over pareidolic.

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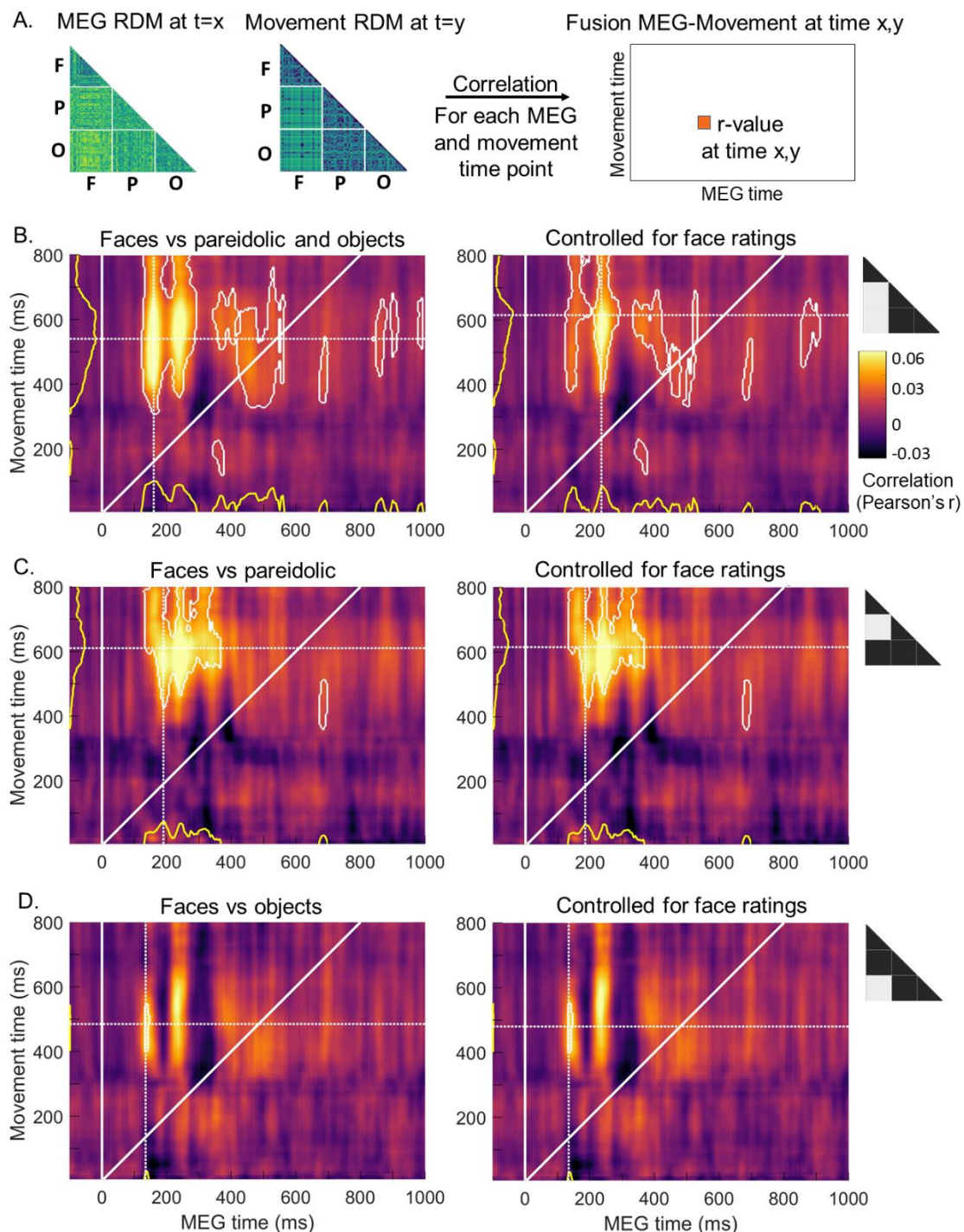
148 **Representational similarity between movement trajectories and MEG.** In fusion analyses, high
149 correlational values indicate shared representational structure across experimental measures,
150 whereas low correlational values indicate rather different representational structures captured by
151 each measure (Figure 2A). Time-time fusion analyses revealed that movement-derived
152 representational geometries are comparable to those from MEG²⁴ in both their structure and their
153 ability to reflect category-specific visual processing among illusory faces, human faces and objects.

154 To understand how the representations of human faces, pareidolic objects (or illusory faces, we use
155 the two terms interchangeably), and objects reflected in movement data evolve over time, we focused
156 our analyses on a subset of the RDMs that best represent the behavioural categorization task: i.e.,
157 faces vs. objects. In practice, this is achieved by selecting the RDM cells that represent dissimilarity
158 between faces and pareidolic objects, and faces and normal objects (Figure 2B, light grey rectangles).
159 Fusion analysis for this subset revealed clusters of significant correlation between MEG and movement
160 representations that were shifted upwards from the diagonal (which represents identical movement
161 and MEG times). This indicates that category representations reflected in movement trajectories
162 lagged in time compared to those captured by MEG data. The peak of significant correlation between
163 the two datasets (defined as the maximum number of significant points projected on each time axis)
164 was located at 160ms and 540ms on the MEG and movement time axes, respectively.

165 Time-time fusion analysis for the RDM subset of faces vs. normal objects (Figure 2D) revealed that the
166 robust neural distinction between faces and objects that arises very early in the MEG response
167 (135ms) exhibited a sustained representational overlap with our mouse trajectory data between 400

168 to 550ms of movement time (peaking at 485ms). The same time-time fusion focused exclusively on
169 the subset faces vs. pareidolic objects (Figure 2C) revealed shared representational structure across
170 the two measures relatively later in time (peaking at 190ms and 610ms on MEG and movement times
171 axis, respectively). The fact that movement-MEG representational overlap for this subset arises
172 comparatively later (55 and 125ms in MEG and movement time, respectively) than for faces vs. objects
173 is highly consistent with Wardle et al.'s²⁴ original report that maximal decoding arises later for faces
174 vs. pareidolic objects (~260ms) than for faces vs. normal objects (~160ms).

175 **Movement trajectories vs. explicit ratings.** Our results also showed that the information captured by
176 movement trajectories go above and beyond the information captured by explicit ratings. We tested
177 *how much* of the fusions between movement and MEG were explained by explicit face ratings' RDM
178 in the original paper²⁴. These face ratings (*face-likeness* of each image in a scale from 0 to 10) were
179 completed by independent observers (N=20) in an online paradigm, see Methods and²⁴ for details.
180 Face ratings indeed explained some of the correlations between movement and MEG representational
181 structures, especially for the subset faces vs. pareidolic objects and objects, where controlled fusion
182 maps showed more constrained regions of significant correlations (Figure 2B, right). For faces vs.
183 pareidolic objects and faces vs. objects, fusion controlled maps remained virtually unchanged when
184 compared to the original ones (Figure 2C-D, right), thus demonstrating that movement captured
185 distinctly different representational information than face ratings.



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187 **Figure 2.** Representational overlap between movement trajectories and MEG responses. **A. MEG-**
 188 **movement fusion.** Fusion analysis evaluates the structural overlap between representations captured
 189 by different brain imaging techniques, behavioural measures and models²⁸. Here we compared the
 190 representational structures captured by MEG and movement data in a time-resolved manner to
 191 elucidate when these measures represent the stimuli (the 96 images dataset) similarly. RDMs from
 192 MEG data constructed by taking 1-correlation between the MEG activation patterns for each pair of
 193 stimuli (see Methods for details) were compared using Pearson's correlation to RDMs constructed
 194 using movement data (Figure 1). Rather than computing correlations on the entire RDM, we selected

195 parts of the RDM, thus focusing on the representational differences between faces and the rest of the
196 stimuli as they hold information about the similarities and differences of the representations of faces,
197 face-like and non-face objects. For each MEG and movement timepoint, we correlated a portion of
198 the RDMs at each MEG and movement time combination. This produced time-time fusion maps with
199 MEG time as the x-axis, movement time as the y-axis and the Pearson's r-value colour-coded. We also
200 calculated the partial correlations between MEG and movement data controlling for the variance
201 explained by face ratings RDMs to check whether the representational similarities between the two
202 could be accounted by simple face ratings (see ²⁴ for details). **B. Faces vs. pareidolic objects and**
203 **objects.** Time-time MEG-movement fusions showed sustained common representational structures
204 peaking at 160ms and 540ms for MEG and movement times respectively (as the maximum number of
205 significant time-time points projected into each coordinate). Fusions controlled for face ratings
206 showed a more restricted pattern of significant correlations peaking at 235ms and 615ms for MEG
207 and movement data, indicating that some of the correlations between MEG and movement data are
208 indeed explained by simple face ratings. **C. Faces vs. pareidolic.** Significant correlations were found to
209 have a later peak than faces vs. pareidolic objects and objects, starting at 190ms and 610ms for MEG
210 and movement times. Correlations controlled for face ratings showed virtually unchanged results
211 compared to the non-controlled maps with significant correlations peaking at 185ms and 615ms for
212 MEG and movement data, thus indicating that the face ratings do not capture the representational
213 structure shared by movement and MEG for the face-pareidolic pairs. **D. Faces vs. objects.** While more
214 constrained than faces vs. pareidolic objects and objects maps, faces vs. objects maps showed a peak
215 at 135ms and 485ms of MEG and movement time, noticeably earlier than the faces vs. pareidolic
216 subset. Fusion maps controlled by ratings showed virtually same results to the non-controlled maps,
217 with significant correlations peaking at 135 and 480ms. White outlines represent significant
218 correlations (one-sample t-test against 0, FDR-corrected for multi-comparisons $q=0.05$, cluster size
219 threshold=50). Yellow lines represent the sum of significant time-time coordinates projected into each
220 axis. Triangles represent the part of the RDMs selected (in light grey) for analyses.

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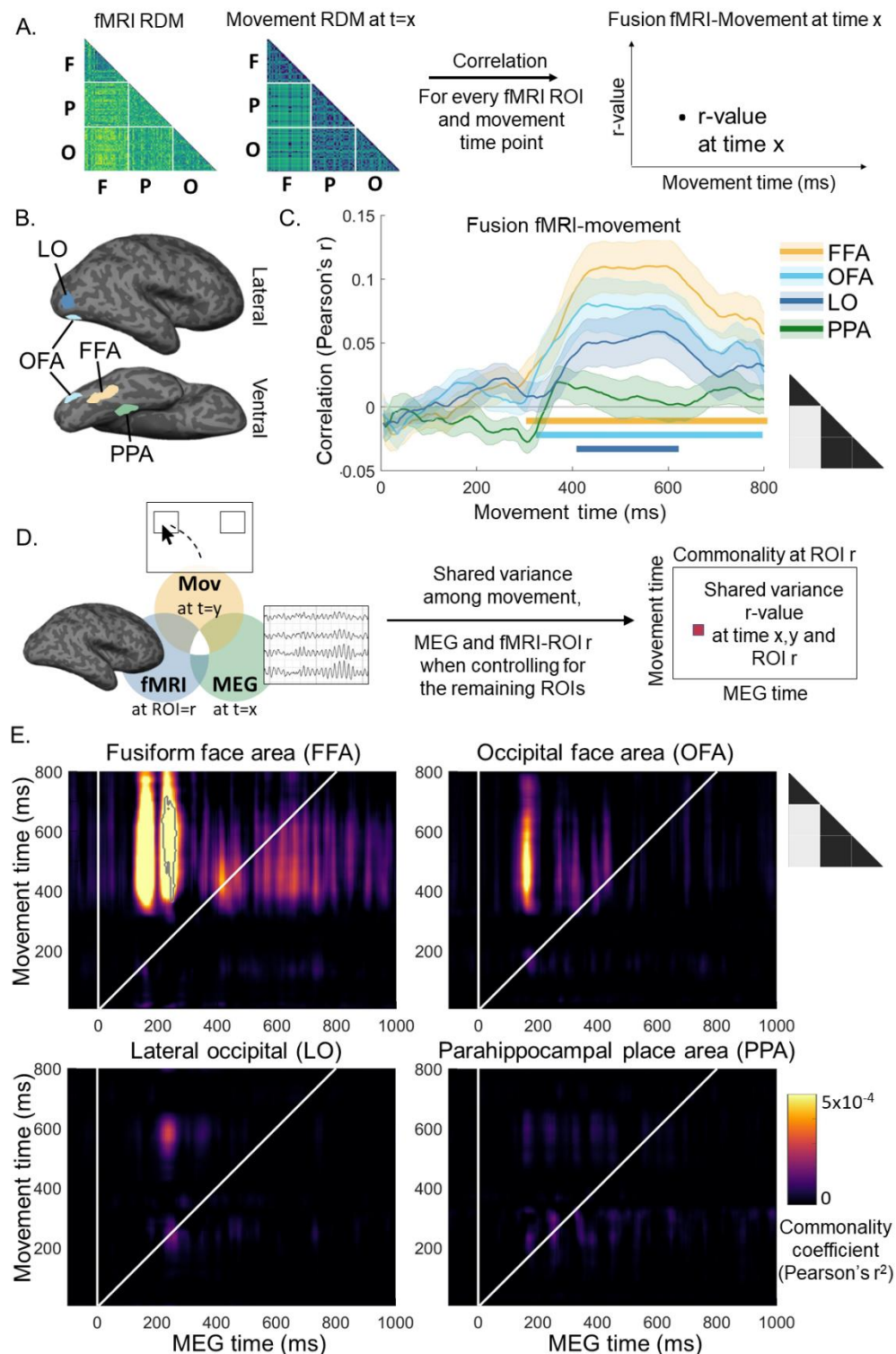
222 **Representational similarity between movement trajectories and fMRI.** Remarkably, fusion analysis
223 with RDMs derived from fMRI data (Figure 3A) revealed that category representations reflected in
224 movement data had structural overlap with those contained in face and object selective brain regions.
225 We used representational structures obtained with fMRI from ²⁴ in four category-selective brain areas:
226 the fusiform face area (FFA), the occipital face area (OFA), the lateral occipital cortex (LO) and the
227 parahippocampal place area (PPA) (Figure, 3B, see Methods for details on ROI definitions). Fusion
228 analyses focused on faces vs. pareidolic objects and objects (Figure 3C) revealed that the
229 representational geometry of faces, pareidolic, and object images as reflected in movement data were
230 significantly correlated with geometries obtained in FFA (from 310ms of movement time), OFA (from
231 330ms) and LO (from 415ms), but not in PPA. These results are consistent with the selectivity of FFA,
232 OFA, and LO brain areas for face and object perception and the role of PPA more oriented towards
233 scene perception.

234 The central contribution of FFA was further confirmed while investigating which brain regions shared
235 common representations with movement and MEG using commonality analysis. Commonality analysis
236 (Figure 3D) allows to identify the unique variance contribution of a single variable or predictor to the
237 variance shared among multiple predictors ^{29,30}. This analysis was used to test which brain areas from
238 FFA, OFA, LO and PPA, contributed the most to the shared variance between movement, MEG and
239 fMRI (see Methods for details). Commonality analyses revealed significant shared movement-MEG-
240 fMRI representations in FFA, but not in other brain areas (Figure 3E). All in all, these results indicate

241 that most of the shared variance between movement, MEG, and fMRI was explained by face-
242 selectiveness in FFA, which is in line with its critical role in face recognition ^{31,32}.

243 While commonality coefficients in OFA were not statistically significant, the latencies seen for FFA and
244 OFA commonality maps could reveal temporal dynamics in the emergence of visual representations
245 in these areas. The similar commonality latencies in OFA and the first responses in FFA could be
246 interpreted as both areas producing face representations concurrently, thus challenging traditional
247 posterior-to-anterior increase in visual hierarchy views ^{33,34}, which have been contested by other
248 studies ³⁵⁻³⁷.

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250

251 **Figure 3.** Representational overlap between movement trajectories and fMRI. **A. fMRI-movement**
 252 **fusion analysis.** We compared the representational structures captured by functional magnetic
 253 resonance imaging (fMRI) and movement in four ROI. RDM on each ROI were constructed by taking 1-
 254 correlation between the BOLD signal for each pair of stimuli (see Methods for details) and were
 255 correlated (Pearson) to RDMs constructed using movement data. **B. Category selective regions.** Four
 256 category selective regions were selected from fMRI recordings: the fusiform face area (FFA), the
 257 occipital face area (OFA), lateral occipital (LO) and parahippocampal place area (PPA). These ROIs were
 258 defined in an independent functional localizer experiment for each participant (see ²⁴ for details). Two

259 of these regions are selective to faces (FFA and OFA), one to objects (LO) and one to scenes (PPA),
260 thus FFA, OFA and LO are expected to represent the differences between the stimuli set. Brains and
261 ROI diagrams were modified from another study of our group and are shown for reference only. **C.**
262 **Movement-fMRI fusions.** Rather than computing correlations on the entire RDM, we selected parts
263 of the RDM to focus on the representational differences between faces and the rest of the stimuli as
264 they hold information about the similarities and differences in coding for faces, face-like and non-face
265 objects (light-grey on the black triangles). For each ROI and movement timepoint, we correlated a
266 portion of the RDMs from both modalities to produce line plots representing the r -values as a function
267 of movement time. **D. Movement-MEG-fMRI commonality analysis rationale.** We used a
268 commonality analysis to investigate which brain areas shared representational structures with
269 movement and MEG data. For each fMRI ROI, we calculated the partial correlation between MEG and
270 movement RDMs when controlled by the variance in ROI= r minus the partial correlation of MEG and
271 movement RDMs when controlled by the variance in all ROIs. **E. Time-time Movement-MEG-fMRI**
272 **commonality maps.** The x and y axes correspond to MEG and movement time, respectively. The
273 commonality coefficient (r^2) is colour-coded. Commonality analyses showed that FFA significantly
274 shared representational structures with MEG and movement. Note that commonality coefficients (r^2)
275 are often small in value (see for instance ^{30,32,38}), as there are likely other sources of variance not
276 accounted for in the models. Therefore, their statistical significance is often considered more
277 important than their magnitude. Black outline represents significant correlations (one-sample one-
278 tailed Wilcoxon signed rank test against 0, FDR-corrected for multi-comparisons $q=0.05$, cluster size
279 threshold=50). Triangles represent the part of the RDMs selected (in light grey) for analyses.

280

281 Discussion

282 Our results show that movement trajectories can be used to track the time course of unfolding neural
283 representations, and that they capture representational structure beyond that reflected in
284 behavioural measures focused on the end point of decisional processes (e.g., stimulus ratings). Our
285 results also highlight the relevance of the Representational Similarity Analysis (RSA) framework to
286 reveal the informational content in movement trajectories and compare movement data with other
287 behavioural and neuroimaging data as well as theoretical models, which opens new avenues to
288 understand human perception using the mouse-tracking paradigm.

289 **Movement trajectories as a window into emerging neural representations.** Our results show that
290 movement trajectories can be modified by cognition even under high time constraint after their
291 execution has started. Moreover, classification movements in our study contained meaningful
292 information about underlying neural representations of stimulus category. It is evidenced in this study
293 by distinct early parts of movement trajectories for faces, illusory faces, and objects in our face vs.
294 object categorization task consistent with their differences in early brain processing. Our results show
295 that time-resolved representational structures derived from movement data were concordant with
296 the unfolding of category representations measured by MEG as early as 120ms after stimulus
297 presentation. Fusion analyses revealed a compelling overlap between stimulus representations
298 reflected in movement and MEG data, with a notable offset between the two measures. The same
299 representational structures evident in MEG data arise in trajectory data after a delay of some 380ms
300 (e.g., for faces vs. pareidolic objects and objects). Importantly, fusion analysis with movement and
301 fMRI data revealed that face, object, and pareidolic object representations derived from movement
302 trajectory data show strong concordance with representations extracted from the BOLD response in
303 the most task-relevant brain regions (i.e., regions with selectivity to faces and objects). Functional
304 MRI-movement fusions indicated significant correlations between movement and FFA, OFA and LO,

305 but not with PPA. These areas are selective to faces (FFA and OFA) and objects (LO)^{31,39}, in contrast to
306 PPA that is involved in scene perception⁴⁰. The central role of FFA was further supported by the
307 commonality analysis that showed that representational structures in FFA explained the shared
308 information content between MEG and movement data better than any other brain area tested.
309 Together, these results demonstrate the suitability of movement trajectories for measuring the time-
310 course of emerging representations in the brain, including their early stages, which opens new
311 possibilities for disentangling in future research stimulus features and processing stages driving
312 human perception.

313 **Movement trajectories contain more information than explicit category ratings.** Our results show
314 that movement trajectories captured representational information that goes beyond that reflected in
315 explicit category ratings. Indeed, when using face ratings from²⁴ to control the correlations between
316 movement and MEG, we found that most of the similarities between movement and MEG
317 representational structures were not explained by face ratings. This result further demonstrates the
318 capacity of movement trajectories to capture time-course information about neural representations
319 and their underlying intermediate representational categories. This is consistent with the ability of
320 mouse-tracking to track non-explicit cognitive processes that otherwise are blurred (or resolved) by
321 testing them explicitly, as in questionnaires or ratings^{10–14,41}. Our results support the assumption that
322 hand movements are continuously updated by the dynamics of competing decisional processes^{42,43},
323 instead of representing their end product as explicit measures do. This property gives mouse-tracking
324 the ability to reveal the dynamics of cognitive processes occurring in parallel and competing with each
325 other. Our results also corroborate work linking neural representations to human reaction time
326 behaviour^{44–48} and speak to the importance of linking neuroimaging data to behaviour^{49–51}. The rich
327 information in movement trajectories may help reveal more subtle links like those between transient
328 intermediate neural processing stages and early decision processes. Our mouse-tracking approach
329 could be integrated in future neuroimaging studies to further explore how dynamic neural
330 representations contribute to decisions.

331 **Representational similarity analysis framework to reveal information in movement trajectories.** Our
332 results underscore the utility of RSA as a powerful framework through which to marry informational
333 content reflected in distinct behavioural and neuroimaging measures. RSA enables comparing
334 information in movement trajectories with that in other systems, MEG, fMRI, and rating data in the
335 present study. Combining mouse-tracking with neuroimaging through RSA has shown to be successful
336 in previous studies to reveal the influence of specific brain areas in stereotypes⁵², cultural-specific
337 facial emotion and contextual associations⁵³ and social biases⁵⁴, but never before in a time-resolved
338 manner as presented here. Time-resolved RSA enabled to test in this study similarities over time
339 between the representational structures of movement trajectories and MEG data, and therefore,
340 reveal the dynamics of neural representations developing after stimulus presentation. Movement
341 trajectories combined with RSA offer endless possibilities to address new research questions as this
342 unit-agnostic approach enables comparing information in movement trajectories with new theoretical
343 models as well as increasingly available public EEG, MEG, fMRI, fNIRS, EMG and eye-tracking datasets.
344 Remarkably, re-using public datasets does not necessarily imply asking the same research questions
345 as the original study. Neuroimaging data from²⁴ used in the current study could be employed with
346 new mouse-tracking tasks and/or participant populations to investigate for instance changes in the
347 representation dynamics of faces, illusory faces and objects with face adaptation⁵⁵ and perceptual
348 deficits⁵⁶.

349 **Conclusion.** The flexibility and potential to answer a diverse range of questions makes the
350 combination of mouse-tracking and publicly available neuroimage datasets through RSA a powerful

351 choice for agile and accessible science. Mouse-tracking is as time and effort efficient as most explicit
352 behavioural measures, while revealing more information, specifically the time-course of covert
353 processes^{6,57}. Widely available and cost-effective, this method combined with RSA offers new
354 opportunities to investigate the dynamical processes underlying human perception.

355

356 **Methods**

357 **Images and neuroimaging data from Wardle et al 2020.** We used the dataset from²⁴ consisting in 96
358 images (<https://osf.io/9g4rz/>). This dataset contained 32 human faces (faces), 32 illusory faces
359 (pareidolic objects) and 32 matched objects (objects). For each illusory face image (pareidolic objects)
360 a matched object image containing the same inanimate object(s) (although not pareidolic objects) was
361 used, making these images comparable in their visual attributes. Human faces were also selected to
362 reflect the high variance of the pareidolic objects and object images, containing different facial
363 expressions, age, ethnicity, orientation and gender.

364 MEG, fMRI and explicit rating data was downloaded from the publicly available repository
365 accompanying their publication at: [https://static-](https://static-content.springer.com/esm/art%3A10.1038%2Fs41467-020-18325-8/MediaObjects/41467_2020_18325_MOESM6_ESM.zip)
366 [content.springer.com/esm/art%3A10.1038%2Fs41467-020-18325-](https://static-content.springer.com/esm/art%3A10.1038%2Fs41467-020-18325-8/MediaObjects/41467_2020_18325_MOESM6_ESM.zip)
367 [8/MediaObjects/41467_2020_18325_MOESM6_ESM.zip](https://static-content.springer.com/esm/art%3A10.1038%2Fs41467-020-18325-8/MediaObjects/41467_2020_18325_MOESM6_ESM.zip).

368 Briefly, MEG recordings from 22 participants were acquired using a 160-channel whole-head KIT MEG
369 system. MEG data were down-sampled to 200Hz and PCA was applied for dimensionality reduction
370 (retaining PCs explaining 99% of variance). MEG RDMs were constructed by taking 1-correlation
371 (Spearman) between the MEG activation patterns for each pair of stimuli at each time point (N=221,
372 from -100 to 1000ms after stimulus presentation). The MEG task consisted in the presentation
373 (200ms) of the 96 visual stimuli (24 repeats of each stimulus). In each trial, images were tilted by 3°
374 (left or right) and participants had to report the tilt direction.

375 Functional MRI recordings from 16 participants were acquired using a 3T Siemens Verio MRI scanner
376 and a 32-channel head coil. A 2D T2*-weighted EPI acquisition sequence was used: TR= 2.5 s, TE=
377 32ms, FA= 80°, voxel size: 2.8 × 2.8 × 2.8 mm. The fMRI task was analogous to the MEG task with the
378 difference that stimuli were presented for 300ms followed by a grey screen to complete a 4s trial. All
379 stimuli were shown once per run and each participant completed 7 runs. Data were slice-time
380 corrected and motion-corrected using AFNI. An independent functional localizer experiment using a
381 different set of images was performed to define the category selective regions: FFA, OFA, LO and PPA.
382 Functional MRI RDMs were built by taking 1-correlation (Spearman) between the BOLD signal for
383 each pair of stimuli (96x96) in each of the four category selective areas.

384

385 **Mouse-tracking participants.** We tested first year students in psychology from Western Sydney
386 University online through the SONA platform in exchange of course credits. Participants gave written
387 informed consent to participate in the study, which was approved by the ethics committee of Western
388 Sydney University. We tested 128 participants, from which, 109 participants completed the entire
389 experiment. From these 109 participants, we discarded 17 participants as they had more than half of
390 trials with no mouse tracking data (either because they chose not to move the mouse or because the
391 data was unable to be collected by the browser). Further 15 participants were discarded as their
392 performance was below 50% on the categorization task (possibly due to not performing the task). In

393 total, datasets from 77 participants (68 females, age=24.4±0.9, righthanded=71, native English
394 speakers=53) were considered for further analyses.

395

396 **Procedure.** We used an online Web browser-based mouse-tracking face vs. object categorization
397 paradigm. The experiment was built upon a publicly available code
398 (https://github.com/mahiluthra/mousetracking_experiment) written in JavaScript using jsPsych 6
399 libraries⁵⁸ and hosted on Pavlovia⁵⁹. Experimenters had no direct interaction with the participants
400 and the experiment ran locally in a web browser on participants own computer⁶⁰. The task started
401 with a central fixation cross and a button marked “Next” at the bottom of the screen that the
402 participant had to press before each trial, thus effectively repositioning the cursor at the bottom of
403 the screen at the start of each trial (see Figure 1). After the “Next” button press, a blank screen with
404 fixation cross was presented for 200ms in order to promote participant’s readiness to start moving.
405 After the blank screen, an image of a human face (face), an object containing an illusory face
406 (pareidolic objects), or a matched object (object) was shown at fixation. Two response boxes were
407 presented in the upper left and right corners of the screen. One of them contained the word “OBJECT”
408 and the other “FACE”. The position of the face and object response boxes was swapped halfway
409 through the experiment (i.e., after two blocks), with the initial position of response boxes
410 counterbalanced across to avoid right/left movement biases. Participants had 800ms to move the
411 cursor to the response box to give the response to the categorization task. The trial ended after 800ms
412 or when participants clicked on one of the boxes. In the mouse-tracking plugin, we set the recording
413 of pointer position coordinates during the 800ms (or until button press) as fast as the local system
414 could do (1ms) which effectively gave readings every 3 to 10ms, which were then linearly interpolated
415 into 5ms temporal resolution. Correct trials were taken as those on which the participant clicked on
416 the correct response box, and those where the cursor landed on the correct response box, even if
417 there was no click. We presented the original 96 images used in²⁴: 32 human faces, 32 illusory faces
418 (i.e., pareidolic objects), and 32 matched objects (see²⁴ for details). To avoid response biases due to
419 a higher likelihood of objects compared to faces, we also included an additional 32 human faces which
420 served to equalise the probability of objects and faces (additional face images not included in
421 analyses). All 128 images appeared in each block; there were four blocks in total and participants could
422 take a self-paced rest break in between each block as necessary.

423

424 **Mouse-tracking movement trajectory analysis.** We analysed mouse-tracking data in MATLAB using
425 in-house custom-developed scripts (<https://osf.io/q3hbp/>). We considered all trials for analyses (both
426 correct and incorrect categorizations) as we hypothesized they jointly represent the unfolding of
427 categorical representations. Empty values at the beginning of the mouse-tracking recordings (due to
428 late onsets of the mouse movement) and the end (due to response box clicks before the 800ms
429 deadline) were filled with NaN. We then linearly interpolated the data to 5ms intervals from 5 to
430 800ms. We then took mouse-tracking horizontal position (x-coordinate) as a time-resolved indicator
431 of the categorization (and thus a time-resolved proxy of visual processing). Per each one of the 96
432 images, we averaged the horizontal position, first across trials within participants (4 trials per image),
433 and then across participants (N=77). We thus considered 29568 individual mouse-tracking trials for
434 analysis. These averaged responses were taken as a descriptor of the time-resolved face/object
435 categorization of a given image. We then used a 20ms moving average window in order to smooth out
436 the mouse-tracking movement trajectories. We used this same smoothing procedure (20ms moving
437 average window) on the MEG data from²⁴.

438

439 **Representational similarity analysis (RSA) of movement data.** Representational similarity analysis
440 allows to compare different experimental measures by abstracting them in the information domain.
441 The way an experimental measure (here pointer horizontal position) differs between two-given stimuli
442 provides an estimation of how similarly (if the magnitudes match) or dissimilarly (if the magnitude
443 difference is high) the two stimuli are represented ²⁷. By calculating the differences between every
444 pair of stimuli, the (dis)similarity matrix provides an estimation of how an experimental measure
445 represents the whole experimental stimuli set. We constructed a representational (dis)similarity
446 matrix (RDM) for each timepoint by calculating the absolute difference in horizontal position for every
447 pair of images yielding 4560 unique pairs (excluding pairs of the same image). This produced 160 RDMs
448 across the interval of 5 to 800ms after stimulus onset. RDMs organized from left to right and top to
449 bottom with face images from positions 1 to 32, then pareidolic from 33 to 64 and then objects from
450 65 to 96. In order to focus on representational distinctions between specific categories, we then
451 subset the RDMs in three different ways: 1) faces vs. pareidolic objects and normal objects (2048
452 unique pairwise comparisons), 2) faces vs. pareidolic objects (1024 unique pairwise comparisons), and
453 3) faces vs. normal objects (1024 unique pairwise comparisons).

454

455 **MEG-movement time-time fusion analysis.** Fusion analyses allow to compare representational
456 structures obtained from different experimental measures (for example, neuroimaging and
457 behaviour) by correlating representational (dis)similarity matrices in a pair by pair basis ^{27,28}. Since
458 both MEG and movement data are time resolved, we compared RDMs from these two modalities at
459 every combination of timepoints (35360 timepoints combinations). This temporal generalization
460 approach (see ⁶¹ for a review) allowed us to identify delays in the onset of representational structures
461 between modalities as well as sustained and repeated structures across time. We calculated the linear
462 correlation (Pearson's *r*) between RDMs from both modalities at every timepoint combination. For
463 face-rating controlled maps, we calculated partial correlations (Pearson's *r*) between MEG and
464 movement RDMs while controlling for RDMs from face ratings.

465

466 **fMRI-movement fusion analysis.** Similar to MEG-movement fusions, fMRI-movement fusion analyses
467 were performed by comparing the representational structures from fMRI and movement via linear
468 correlation (Pearson's *r*). While fMRI data from ²⁴ were not time resolved, there were 4 regions of
469 interest (ROI) considered (FFA, OFA, LO and PPA). Correlations between RDMs for every fMRI ROI and
470 movement timepoint were calculated to obtain a correlation value as a function of movement time.

471

472 **Movement-MEG-fMRI commonality analysis.** In order to understand which brain areas from the four
473 fMRI ROI shared information with the representational structures from the combination of movement
474 and MEG, we used a commonality analysis ^{29,30}. Commonality analysis allows to identify the unique
475 variance contribution of a single variable or predictor to the variance shared among multiple
476 predictors. This method has successfully been used in conjunction with RSA to compare how different
477 predictors in the form of neuroimaging methods, models and tasks explain shared variance ^{30,32,38,62}.
478 Here, we focused on how 4 predictors, the fMRI ROI: FFA, OFA, LO and PPA, contributed to the shared
479 variance between movement, MEG and fMRI. For each ROI (for example ROI1), we performed a
480 commonality analysis by comparing the semi-partial correlations of all model variables except for the
481 ROI whose contribution we wanted to isolate (Mov, MEG, ROI2, ROI3, ROI4), with the semi-partial

482 correlation of all the model variables, including the selected ROI (Mov, MEG, ROI1, ROI2, ROI3, ROI4).
483 We performed this analysis for each fMRI ROI as follows:

484

$$485 C_{(\text{Mov,MEG,ROI1})} = R^2_{(\text{Mov,MEG,ROI2,ROI3,ROI4})} - R^2_{(\text{Mov,MEG,ROI1,ROI2,ROI3,ROI4})}$$

$$486 C_{(\text{Mov,MEG,ROI2})} = R^2_{(\text{Mov,MEG,ROI1,ROI3,ROI4})} - R^2_{(\text{Mov,MEG,ROI1,ROI2,ROI3,ROI4})}$$

$$487 C_{(\text{Mov,MEG,ROI3})} = R^2_{(\text{Mov,MEG,ROI1,ROI2,ROI4})} - R^2_{(\text{Mov,MEG,ROI1,ROI2,ROI3,ROI4})}$$

$$488 C_{(\text{Mov,MEG,ROI4})} = R^2_{(\text{Mov,MEG,ROI1,ROI2,ROI3})} - R^2_{(\text{Mov,MEG,ROI1,ROI2,ROI3,ROI4})}$$

489

490 **Statistical inference.** Time-time MEG-movement fusion maps and commonality maps' correlations
491 were tested via one-sample tests against 0 (h_0 : absence of correlation). We used two-sided t-tests for
492 MEG-movement fusion maps and one-sided Wilcoxon signed rank tests for commonality maps across
493 MEG participants ($N=22$). False discovery rate (FDR) ⁶³ was used to control for multi-comparisons (type
494 I errors or false-positives) with a $q=0.05$. Additionally, a cluster size of 50 time-time coordinates was
495 set as the minimum size threshold for significance to avoid spurious results. Movement-fMRI fusions
496 were tested using right-sided, one sample t-tests against 0 across fMRI participants ($N=16$) and multi-
497 comparisons across movement timepoints were also controlled using false discovery rate ($q=0.05$).

498

499 **Data and code availability.** Mouse-tracking data and MATLAB code to produce all results and figures
500 are available at: <https://osf.io/q3hbp/>

501

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503

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